

## 4 M-BIT DYNAMIC RAM 1 M-WORD BY 4-BIT, FAST PAGE MODE

### Description

The  $\mu$ PD424400 is a 1 048 576 words by 4 bits dynamic CMOS RAM. The fast page mode capability realize high speed access and low power consumption.

These are packed in 26-pin plastic TSOP(II), 26-pin plastic SOJ and 20-pin plastic ZIP.

### Features

- 1 048 576 words by 4 bits organization
- Single +5.0 V $\pm$ 10 % power supply
- Fast access and cycle time

Part number	Power consumption		Access time (MAX.)	R/W cycle time (MIN.)	Fast page mode cycle time (MIN.)
	Active (MAX.)	Standby(MAX.)			
$\mu$ PD424400-60	660 mW	5.5 mW (CMOS level input)	60 ns	120 ns	40 ns
$\mu$ PD424400-70	550 mW		70 ns	140 ns	45 ns
$\mu$ PD424400-80	495 mW		80 ns	160 ns	50 ns
$\mu$ PD424400-10	440 mW		100 ns	190 ns	60 ns

- 1 024 refresh cycles/16 ms
- CAS before RAS refresh, RAS only refresh, Hidden refresh
- Multiplexed address inputs ..... Row address : A0 to A9, Column address : A0 to A9

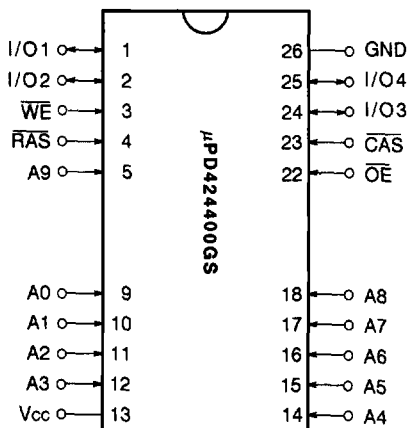
Ordering Information

Part number	Access time (MAX.)	Package	Quality grade
μPD424400GS-60	60 ns	26-pin Plastic TSOP (II) (300 mil)	Standard
μPD424400GS-70	70 ns		
μPD424400GS-80	80 ns		
μPD424400GS-10	100 ns		
μPD424400LA-60	60 ns	26-pin Plastic SOJ (300 mil)	
μPD424400LA-70	70 ns		
μPD424400LA-80	80 ns		
μPD424400LA-10	100 ns		
μPD424400V-60	60 ns	20-pin Plastic ZIP (400 mil)	
μPD424400V-70	70 ns		
μPD424400V-80	80 ns		
μPD424400V-10	100 ns		

Please refer to "Quality grade on NEC Semiconductor Devices" (Document number IEI-1209) published by NEC Corporation to know the specification of quality grade on the devices and its recommended applications.

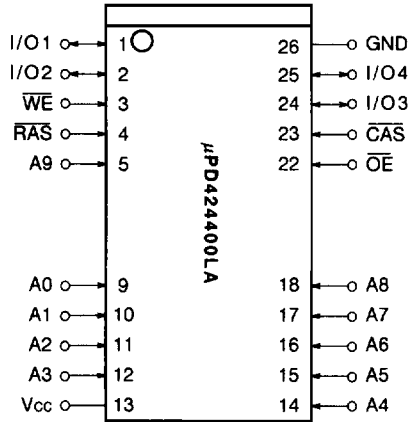
Pin Configurations (Marking Side)

26-pin Plastic TSOP(II) (300 mil)

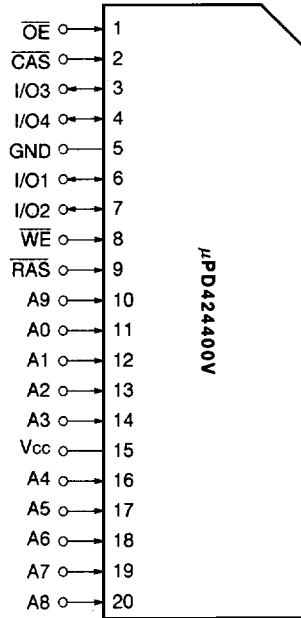


- A0 to A9 : Address Inputs
- I/O1 to I/O4 : Data Inputs/Outputs
- $\overline{\text{RAS}}$  : Row Address Strobe
- $\overline{\text{CAS}}$  : Column Address Strobe
- $\overline{\text{WE}}$  : Write Enable
- $\overline{\text{OE}}$  : Output Enable
- Vcc : Power Supply
- GND : Ground

26-pin Plastic SOJ (300 mil)

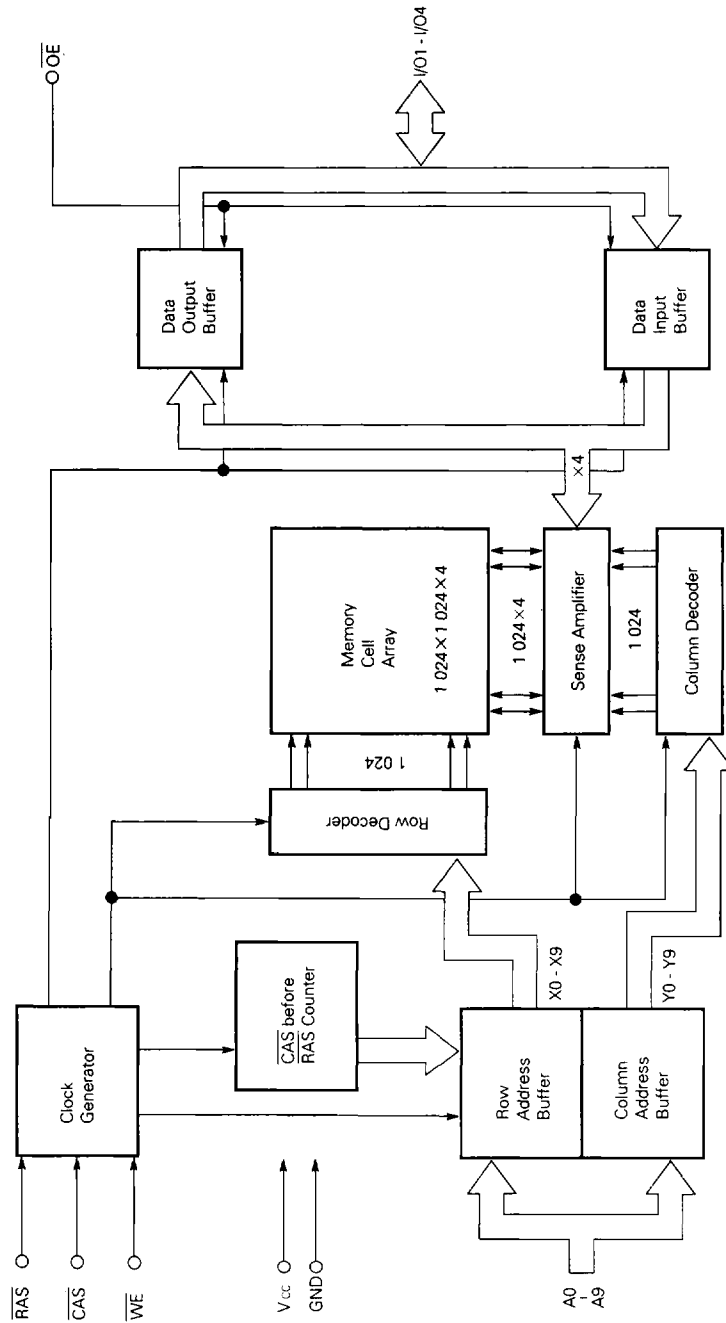


20-pin Plastic ZIP (400 mil)



- A0 to A9 : Address Inputs
- I/O1 to I/O4 : Data Inputs/Outputs
- $\overline{RAS}$  : Row Address Strobe
- $\overline{CAS}$  : Column Address Strobe
- $\overline{WE}$  : Write Enable
- $\overline{OE}$  : Output Enable
- Vcc : Power Supply
- GND : Ground

Block Diagram



**Input/Output Pin Functions**

The μPD424400 has input pins  $\overline{\text{RAS}}$ ,  $\overline{\text{CAS}}$ ,  $\overline{\text{WE}}$ ,  $\overline{\text{OE}}$ , A0 to A9 and input/output pins I/O1 to I/O4.

Pin Name	Input/Output	Function
$\overline{\text{RAS}}$ (Row address strobe)	Input	$\overline{\text{RAS}}$ activates the sense amplifier by latching a row address and selecting a corresponding word line. It refreshes memory cell array of one line selected by the row address. It also selects the following function. • CAS before RAS refresh
$\overline{\text{CAS}}$ (Column address strobe)		$\overline{\text{CAS}}$ activates data input/output circuit by latching column address and selecting a digit line connected with the sense amplifier.
A0 to A9 (Address input)		Address bus. Input total 20-bit of address signal, upper 10-bit and lower 10-bit in sequence (address multiplex method). Therefore, one word is selected from 1 048 576-word by 4-bit memory cell array. In actual operation, latch row address by specifying row address and activating $\overline{\text{RAS}}$ . Then, switch the address bus to column address and activate $\overline{\text{CAS}}$ . Each address is taken into the device when $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ are activated. Therefore, the address input setup time ( $t_{ASR}$ , $t_{ASC}$ ) and hold time ( $t_{RAH}$ , $t_{CAH}$ ) are specified for the activation of $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ .
$\overline{\text{WE}}$ (Write enable)		Write control signal. Write operation is executed by activating $\overline{\text{RAS}}$ , $\overline{\text{CAS}}$ and $\overline{\text{WE}}$ .
$\overline{\text{OE}}$ (Output enable)		Read control signal. Read operation can be executed by activating $\overline{\text{RAS}}$ , $\overline{\text{CAS}}$ and $\overline{\text{OE}}$ . If $\overline{\text{WE}}$ is activated during read operation, $\overline{\text{OE}}$ is to be ineffective in the device. Therefore, read operation cannot be executed.
I/O1 to I/O4 (Data input/output)	Input/Output	4-bit data bus. I/O1 to I/O4 are used to input/output data.

**Electrical Specifications**

- All voltages are referenced to GND.
- After power up, wait more than 100 μs and then, execute eight  $\overline{\text{CAS}}$  before  $\overline{\text{RAS}}$  or  $\overline{\text{RAS}}$  only refresh cycles as dummy cycles to initialize internal circuit.

**Absolute Maximum Ratings**

Parameter	Symbol	Condition	Rating	Unit
Voltage on Any Pin Relative to GND	$V_T$		-1.0 to +7.0	V
Supply Voltage	$V_{CC}$		-1.0 to +7.0	V
Output Current	$I_O$		50	mA
Power Dissipation	$P_D$		1	W
Operating Temperature	$T_{opt}$		0 to +70	°C
Storage Temperature	$T_{stg}$		-55 to +125	°C

**Caution** Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

**Recommended Operating Conditions**

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Supply Voltage	$V_{CC}$		4.5	5.0	5.5	V
High Level Input Voltage	$V_{IH}$		2.4		$V_{CC} + 1.0$	V
Low Level Input Voltage	$V_{IL}$		-1.0		+0.8	V
Ambient Temperature	$T_a$		0		70	°C

**Capacitance ( $T_a = 25\text{ }^\circ\text{C}$ ,  $f = 1\text{ MHz}$ )**

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input Capacitance	$C_{I1}$	Address			5	pF
	$C_{I2}$	$\overline{\text{RAS}}$ , $\overline{\text{CAS}}$ , $\overline{\text{WE}}$ , $\overline{\text{OE}}$			7	pF
Data Input/Output Capacitance	$C_{I/O}$	I/O			7	pF

DC Characteristics (Recommended operating conditions unless otherwise noted)

Parameter	Symbol	Test Condition	MIN.	TYP.	MAX.	Unit	Notes
Operating current	I <sub>CC1</sub>	$\overline{\text{RAS}}, \overline{\text{CAS}}$ Cycling $t_{\text{RC}} = t_{\text{RC}}(\text{MIN.})$ $I_o = 0 \text{ mA}$	$t_{\text{RAC}} = 60 \text{ ns}$		120	mA	1, 2, 3
			$t_{\text{RAC}} = 70 \text{ ns}$		100		
			$t_{\text{RAC}} = 80 \text{ ns}$		90		
			$t_{\text{RAC}} = 100 \text{ ns}$		80		
Standby current	I <sub>CC2</sub>	$\overline{\text{RAS}}, \overline{\text{CAS}} \geq V_{\text{IH}}(\text{MIN.}), I_o = 0 \text{ mA}$			2	mA	
		$\overline{\text{RAS}}, \overline{\text{CAS}} \geq V_{\text{CC}} - 0.2 \text{ V}, I_o = 0 \text{ mA}$			1		
RAS only refresh current	I <sub>CC3</sub>	$\overline{\text{RAS}}$ Cycling, $\overline{\text{CAS}} \geq V_{\text{IH}}(\text{MIN.})$ $t_{\text{RC}} = t_{\text{RC}}(\text{MIN.}), I_o = 0 \text{ mA}$	$t_{\text{RAC}} = 60 \text{ ns}$		120	mA	1, 2, 3, 4
			$t_{\text{RAC}} = 70 \text{ ns}$		100		
			$t_{\text{RAC}} = 80 \text{ ns}$		90		
			$t_{\text{RAC}} = 100 \text{ ns}$		80		
Operating current (Fast page mode)	I <sub>CC4</sub>	$\overline{\text{RAS}} \leq V_{\text{IL}}(\text{MAX.}), \overline{\text{CAS}}$ Cycling $t_{\text{PC}} = t_{\text{PC}}(\text{MIN.}), I_o = 0 \text{ mA}$	$t_{\text{RAC}} = 60 \text{ ns}$		90	mA	1, 2, 5
			$t_{\text{RAC}} = 70 \text{ ns}$		80		
			$t_{\text{RAC}} = 80 \text{ ns}$		70		
			$t_{\text{RAC}} = 100 \text{ ns}$		60		
CAS before RAS refresh current	I <sub>CC5</sub>	$\overline{\text{RAS}}$ Cycling $t_{\text{RC}} = t_{\text{RC}}(\text{MIN.})$ $I_o = 0 \text{ mA}$	$t_{\text{RAC}} = 60 \text{ ns}$		120	mA	1, 2
			$t_{\text{RAC}} = 70 \text{ ns}$		100		
			$t_{\text{RAC}} = 80 \text{ ns}$		90		
			$t_{\text{RAC}} = 100 \text{ ns}$		80		
Input leakage current	I <sub>I(L)</sub>	$V_i = 0 \text{ to } 5.5 \text{ V}$ All other pins not under test = 0 V	-10		+10	μA	
Output leakage current	I <sub>O(L)</sub>	$V_o = 0 \text{ to } 5.5 \text{ V}$ Output is disabled (Hi-Z)	-10		+10	μA	
High level output voltage	V <sub>OH</sub>	$I_o = -5.0 \text{ mA}$	2.4			V	
Low level output voltage	V <sub>OL</sub>	$I_o = +4.2 \text{ mA}$			0.4	V	

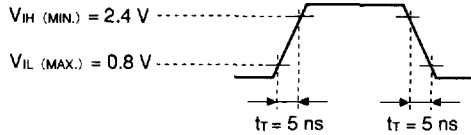
- Notes**
1. I<sub>CC1</sub>, I<sub>CC3</sub>, I<sub>CC4</sub> and I<sub>CC5</sub> depend on cycle rates (t<sub>RC</sub> and t<sub>PC</sub>).
  2. Specified values are obtained with outputs unloaded.
  3. I<sub>CC1</sub> and I<sub>CC3</sub> are measured assuming that address can be changed once or less during  $\overline{\text{RAS}} \leq V_{\text{IL}}(\text{MAX.})$  and  $\overline{\text{CAS}} \geq V_{\text{IH}}(\text{MIN.})$ .
  4. I<sub>CC3</sub> is measured assuming that all column address inputs are held at either high or low.
  5. I<sub>CC4</sub> is measured assuming that all column address inputs are switched only once during each fast page cycle.



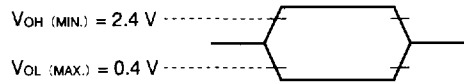
**AC Characteristics (Recommended Operating Conditions unless otherwise noted)**

**AC Characteristics Test Conditions**

(1) Input timing specification



(2) Output timing specification



(3) Loading conditions are 100 pF + 2 TTLs.

**Common to Read, Write, Read Modify Write Cycle**

Parameter	Symbol	trac = 60 ns		trac = 70 ns		trac = 80 ns		trac = 100 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Read / Write Cycle Time	trc	120	-	140	-	160	-	190	-	ns	
RAS Precharge Time	trp	50	-	60	-	70	-	80	-	ns	
CAS Precharge Time	tcpn	10	-	10	-	10	-	10	-	ns	
RAS Pulse Width	tr <sub>AS</sub>	60	10 000	70	10 000	80	10 000	100	10 000	ns	
CAS Pulse Width	tc <sub>AS</sub>	15	10 000	20	10 000	20	10 000	25	10 000	ns	
RAS Hold Time	tr <sub>SH</sub>	20	-	20	-	20	-	25	-	ns	
CAS Hold Time	tc <sub>SH</sub>	60	-	70	-	80	-	100	-	ns	
RAS to CAS Delay Time	tr <sub>CD</sub>	20	40	20	50	25	60	25	75	ns	1
RAS to Column Address Delay Time	tr <sub>AD</sub>	15	30	15	35	17	40	17	50	ns	1
CAS to RAS Precharge Time	tc <sub>RP</sub>	10	-	10	-	10	-	10	-	ns	2
Row Address Setup Time	t <sub>ASR</sub>	0	-	0	-	0	-	0	-	ns	
Row Address Hold Time	t <sub>RAH</sub>	10	-	10	-	12	-	12	-	ns	
Column Address Setup Time	t <sub>ASC</sub>	0	-	0	-	0	-	0	-	ns	
Column Address Hold Time	t <sub>CAH</sub>	15	-	15	-	15	-	20	-	ns	
OE Lead Time Referenced to RAS	t <sub>OES</sub>	0	-	0	-	0	-	0	-	ns	
CAS to Data Setup Time	t <sub>CLZ</sub>	0	-	0	-	0	-	0	-	ns	
OE to Data Setup Time	t <sub>OLZ</sub>	0	-	0	-	0	-	0	-	ns	
OE to Data Delay Time	t <sub>OED</sub>	15	-	15	-	20	-	25	-	ns	
Transition Time (Rise and Fall)	t <sub>T</sub>	3	50	3	50	3	50	3	50	ns	
Refresh Time	t <sub>REF</sub>	-	16	-	16	-	16	-	16	ms	

**Notes** 1. For read cycles, access time is defined as follows:

Input Conditions	Access Time	Access Time from RAS
$t_{RAD} \leq t_{RAD}(MAX.)$ and $t_{RCD} \leq t_{RCD}(MAX.)$	$t_{RAC}(MAX.)$	$t_{RAC}(MAX.)$
$t_{RAD} > t_{RAD}(MAX.)$ and $t_{RCD} \leq t_{RCD}(MAX.)$	$t_{AA}(MAX.)$	$t_{RAD} + t_{AA}(MAX.)$
$t_{RCD} > t_{RCD}(MAX.)$	$t_{CAC}(MAX.)$	$t_{RCD} + t_{CAC}(MAX.)$

$t_{RAD}(MAX.)$  and  $t_{RCD}(MAX.)$  are specified as reference points only ; they are not restrictive operating parameters. They are used to determine which access time( $t_{RAC}$ ,  $t_{AA}$  or  $t_{CAC}$ ) is to be used for finding out when output data will be available. Therefore, the input conditions  $t_{RAD} \geq t_{RAD}(MAX.)$  and  $t_{RCD} \geq t_{RCD}(MAX.)$  will not cause any operation problems.

2.  $t_{CRP(MIN)}$  requirement is applied for  $\overline{RAS}$ ,  $\overline{CAS}$  cycles preceded by any cycle.

**Read Cycle**

Parameter	Symbol	$t_{RAC} = 60 \text{ ns}$		$t_{RAC} = 70 \text{ ns}$		$t_{RAC} = 80 \text{ ns}$		$t_{RAC} = 100 \text{ ns}$		Unit	Notes
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Access Time from $\overline{RAS}$	$t_{RAC}$	-	60	-	70	-	80	-	100	ns	1
Access Time from $\overline{CAS}$	$t_{CAC}$	-	15	-	20	-	20	-	25	ns	1
Access Time from Column Address	$t_{AA}$	-	30	-	35	-	40	-	50	ns	1
Access Time from $\overline{OE}$	$t_{OEA}$	-	20	-	20	-	20	-	25	ns	
Column Address Lead Time Referenced to $\overline{RAS}$	$t_{RAL}$	30	-	35	-	40	-	50	-	ns	
Read Command Setup Time	$t_{RCS}$	0	-	0	-	0	-	0	-	ns	
Read Command Hold Time Referenced to $\overline{RAS}$	$t_{RRH}$	10	-	10	-	10	-	10	-	ns	2
Read Command Hold Time Referenced to $\overline{CAS}$	$t_{RCH}$	0	-	0	-	0	-	0	-	ns	2
Output Buffer Turn-off Delay Time from $\overline{OE}$	$t_{OEZ}$	0	15	0	15	0	20	0	25	ns	3
Output Buffer Turn-off Delay Time from $\overline{CAS}$	$t_{OFF}$	0	15	0	15	0	20	0	25	ns	3

**Notes** 1. For read cycles, access time is defined as follows:

Input Conditions	Access Time	Access Time from $\overline{RAS}$
$t_{RAD} \leq t_{RAD(MAX)}$ and $t_{RCD} \leq t_{RCD(MAX)}$	$t_{RAC(MAX)}$	$t_{RAC(MAX)}$
$t_{RAD} > t_{RAD(MAX)}$ and $t_{RCD} \leq t_{RCD(MAX)}$	$t_{AA(MAX)}$	$t_{RAD} + t_{AA(MAX)}$
$t_{RCD} > t_{RCD(MAX)}$	$t_{CAC(MAX)}$	$t_{RCD} + t_{CAC(MAX)}$

$t_{RAD(MAX)}$  and  $t_{RCD(MAX)}$  are specified as reference points only ; they are not restrictive operating parameters. They are used to determine which access time( $t_{RAC}$ ,  $t_{AA}$  or  $t_{CAC}$ ) is to be used for finding out when output data will be available. Therefore, the input conditions  $t_{RAD} \geq t_{RAD(MAX)}$  and  $t_{RCD} \geq t_{RCD(MAX)}$  will not cause any operation problems.

2. Either  $t_{RCH(MIN)}$  or  $t_{RRH(MIN)}$  should be met in read cycles.
3.  $t_{OFF(MAX)}$  and  $t_{OEZ(MAX)}$  define the time when the output achieves the condition of Hi - Z and is not referenced to  $V_{OH}$  or  $V_{OL}$ .

**Write Cycle**

Parameter	Symbol	t <sub>TRAC</sub> = 60 ns		t <sub>TRAC</sub> = 70 ns		t <sub>TRAC</sub> = 80 ns		t <sub>TRAC</sub> = 100 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
$\overline{WE}$ Hold Time Referenced to $\overline{CAS}$	t <sub>WCH</sub>	15	-	15	-	15	-	20	-	ns	1
$\overline{WE}$ Pulse Width	t <sub>WP</sub>	15	-	15	-	15	-	20	-	ns	1
$\overline{WE}$ Lead Time Referenced to $\overline{RAS}$	t <sub>RWL</sub>	20	-	20	-	20	-	25	-	ns	
$\overline{WE}$ Lead Time Referenced to $\overline{CAS}$	t <sub>CWL</sub>	15	-	15	-	15	-	20	-	ns	
$\overline{WE}$ Setup Time	t <sub>WCS</sub>	0	-	0	-	0	-	0	-	ns	2
$\overline{OE}$ Hold Time	t <sub>OEH</sub>	0	-	0	-	0	-	0	-	ns	
Data-in Setup Time	t <sub>DS</sub>	0	-	0	-	0	-	0	-	ns	3
Data-in Hold Time	t <sub>DH</sub>	15	-	15	-	15	-	20	-	ns	3

- Notes**
1. t<sub>WP(MIN.)</sub> is applied for late write cycles or read modify write cycles. In early write cycles, t<sub>WCH(MIN.)</sub> should be met.
  2. If t<sub>WCS</sub> ≥ t<sub>WCS(MIN.)</sub>, the cycle is an early write cycle and the data out will remain Hi - Z through the entire cycle.
  3. t<sub>DS(MIN.)</sub> and t<sub>DH(MIN.)</sub> are referenced to the  $\overline{CAS}$  falling edge in early write cycles. In late write cycles and read modify write cycles, they are referenced to the  $\overline{WE}$  falling edge.

**Read Modify Write Cycle**

Parameter	Symbol	t <sub>TRAC</sub> = 60 ns		t <sub>TRAC</sub> = 70 ns		t <sub>TRAC</sub> = 80 ns		t <sub>TRAC</sub> = 100 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Read Modify Write Cycle Time	t <sub>RWC</sub>	165	-	185	-	210	-	250	-	ns	
$\overline{RAS}$ to $\overline{WE}$ Delay Time	t <sub>RWD</sub>	80	-	90	-	105	-	130	-	ns	1
$\overline{CAS}$ to $\overline{WE}$ Delay Time	t <sub>CWD</sub>	40	-	40	-	45	-	55	-	ns	1
Column Address to $\overline{WE}$ Delay Time	t <sub>AWD</sub>	50	-	55	-	65	-	80	-	ns	1

- Note 1.** If t<sub>WCS</sub> ≥ t<sub>WCS(MIN.)</sub>, the cycle is an early write cycle and the data out will remain Hi - Z through the entire cycle. If t<sub>RWD</sub> ≥ t<sub>RWD(MIN.)</sub>, t<sub>CWD</sub> ≥ t<sub>CWD(MIN.)</sub>, t<sub>AWD</sub> ≥ t<sub>AWD(MIN.)</sub>, and t<sub>CPWD</sub> ≥ t<sub>CPWD(MIN.)</sub>, the cycle is a read modify write cycle and the data out will contain data read from the selected cell. If neither of the above conditions is met, the state of the data out is indeterminate.

**Fast Page Mode**

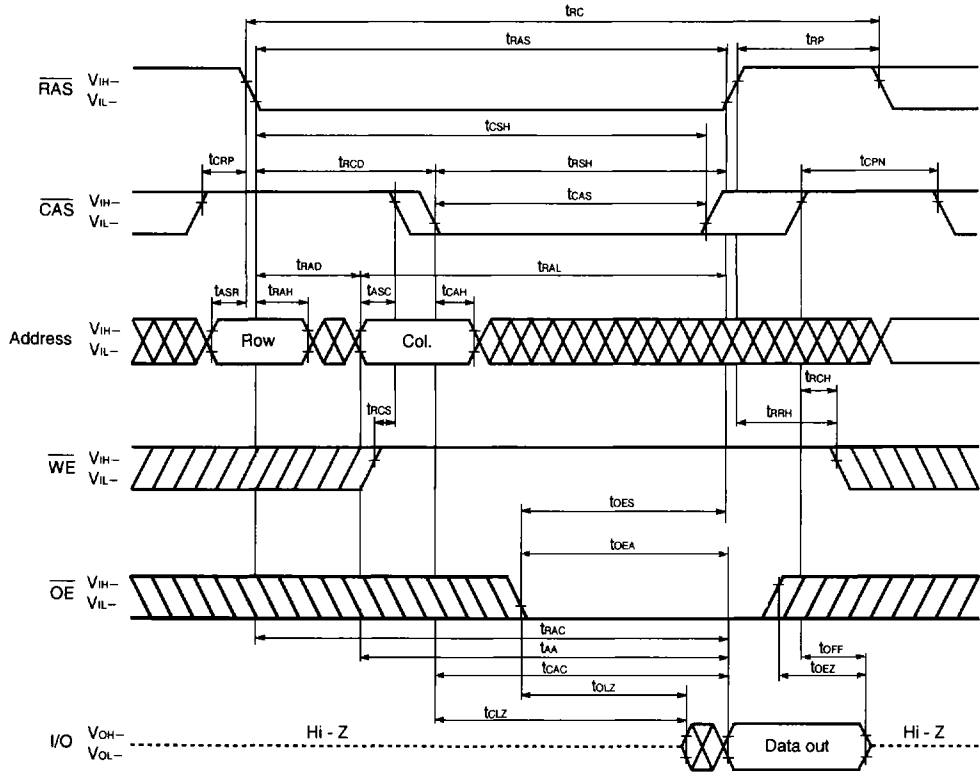
Parameter	Symbol	t <sub>RAC</sub> = 60 ns		t <sub>RAC</sub> = 70 ns		t <sub>RAC</sub> = 80 ns		t <sub>RAC</sub> = 100 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Fast Page Mode Cycle Time	t <sub>PC</sub>	40	-	45	-	50	-	60	-	ns	
Access Time from $\overline{\text{CAS}}$ Precharge	t <sub>ACP</sub>	-	35	-	40	-	45	-	55	ns	
$\overline{\text{RAS}}$ Pulse Width	t <sub>RASP</sub>	60	125 000	70	125 000	80	125 000	100	125 000	ns	
$\overline{\text{CAS}}$ Precharge Time	t <sub>CP</sub>	10	-	10	-	10	-	10	-	ns	
RAS Hold Time from $\overline{\text{CAS}}$ Precharge	t <sub>RHCP</sub>	35	-	40	-	45	-	55	-	ns	
Read Modify Write Cycle Time	t <sub>PRWC</sub>	85	-	90	-	100	-	120	-	ns	
$\overline{\text{CAS}}$ Precharge to $\overline{\text{WE}}$ Delay Time	t <sub>CPWD</sub>	55	-	60	-	70	-	85	-	ns	1

**Note 1.** If  $t_{\text{WCS}} \geq t_{\text{WCS(MIN.)}}$ , the cycle is an early write cycle and the data out will remain Hi - Z through the entire cycle. If  $t_{\text{RWD}} \geq t_{\text{RWD(MIN.)}}$ ,  $t_{\text{CWD}} \geq t_{\text{CWD(MIN.)}}$ ,  $t_{\text{AWD}} \geq t_{\text{AWD(MIN.)}}$ , and  $t_{\text{CPWD}} \geq t_{\text{CPWD(MIN.)}}$ , the cycle is a read modify write cycle and the data out will contain data read from the selected cell. If neither of the above conditions is met, the state of the data out is indeterminate.

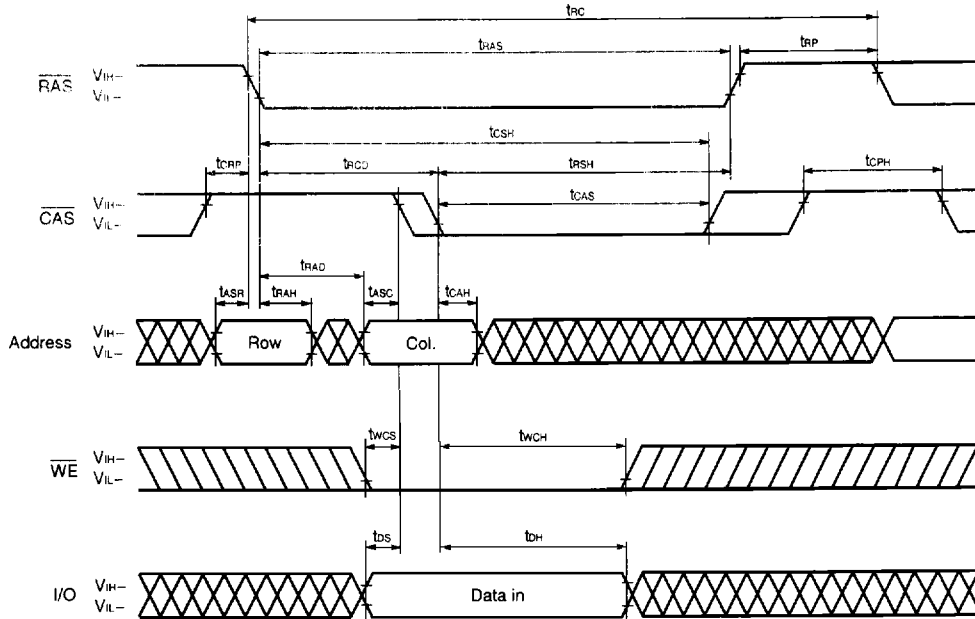
**Refresh Cycle**

Parameter	Symbol	t <sub>RAC</sub> = 60 ns		t <sub>RAC</sub> = 70 ns		t <sub>RAC</sub> = 80 ns		t <sub>RAC</sub> = 100 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
$\overline{\text{CAS}}$ Setup Time	t <sub>CSR</sub>	10	-	10	-	10	-	10	-	ns	
$\overline{\text{CAS}}$ Hold Time ( $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ Refresh)	t <sub>CHR</sub>	15	-	15	-	15	-	20	-	ns	
RAS Precharge $\overline{\text{CAS}}$ Hold Time	t <sub>RPC</sub>	10	-	10	-	10	-	10	-	ns	
$\overline{\text{WE}}$ Setup Time	t <sub>WSR</sub>	10	-	10	-	10	-	10	-	ns	
$\overline{\text{WE}}$ Hold Time	t <sub>WHR</sub>	15	-	15	-	15	-	20	-	ns	

Read Cycle

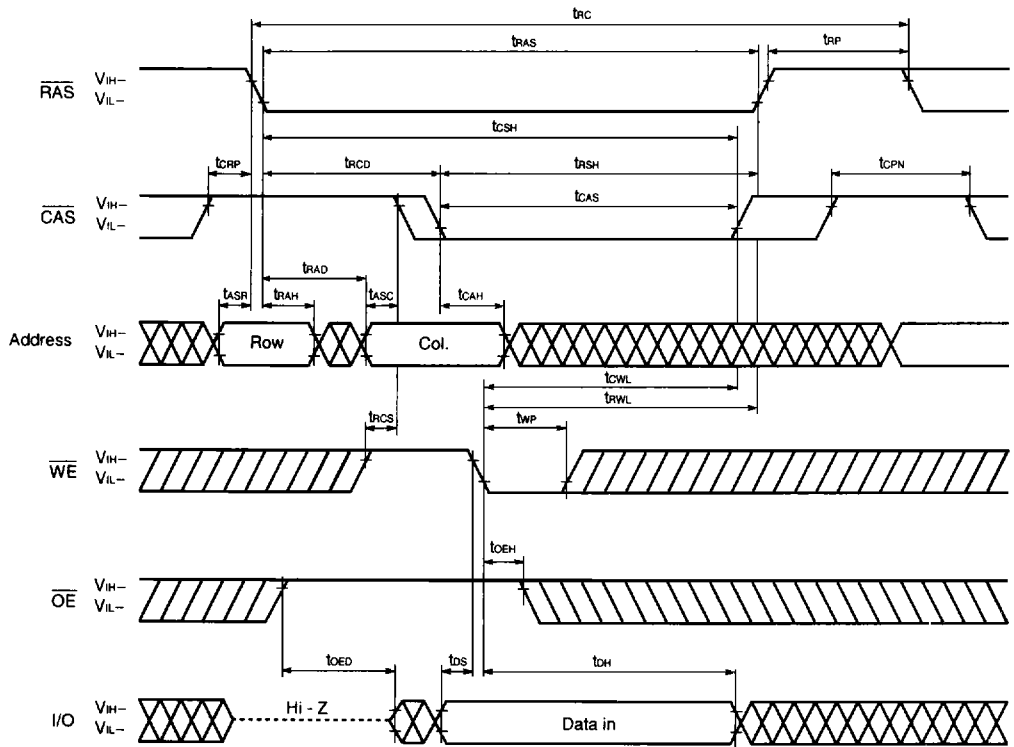


Early Write Cycle

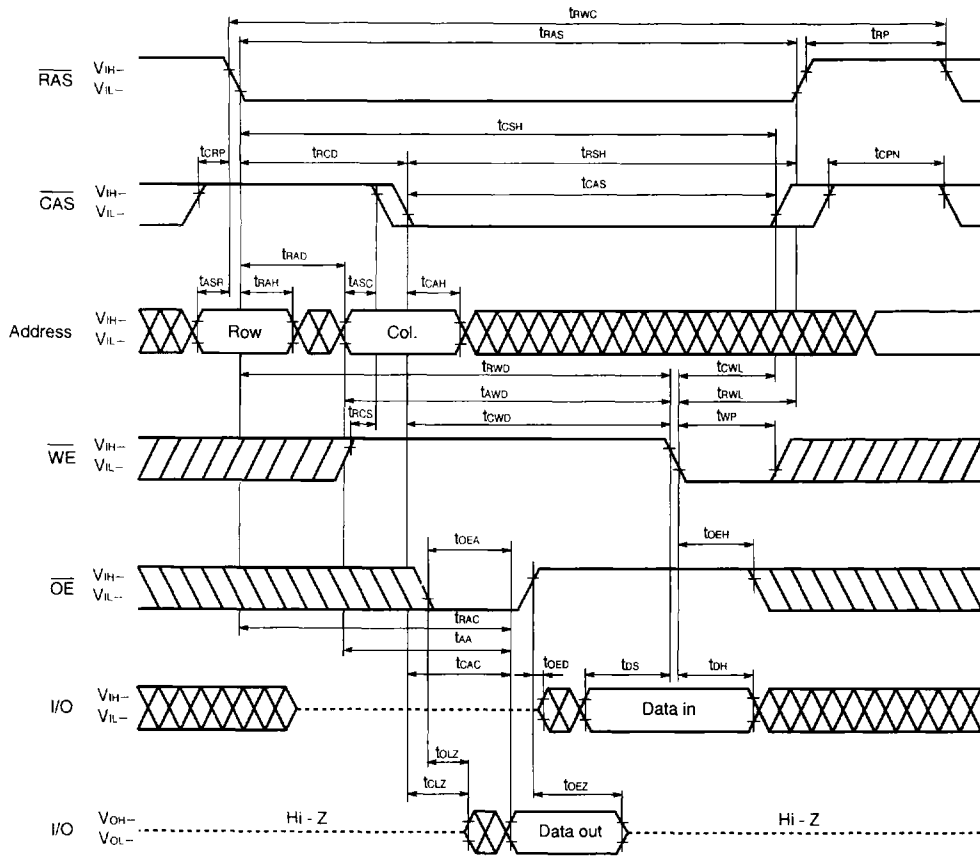


Remark  $\overline{OE}$  : Don't care

Late Write Cycle

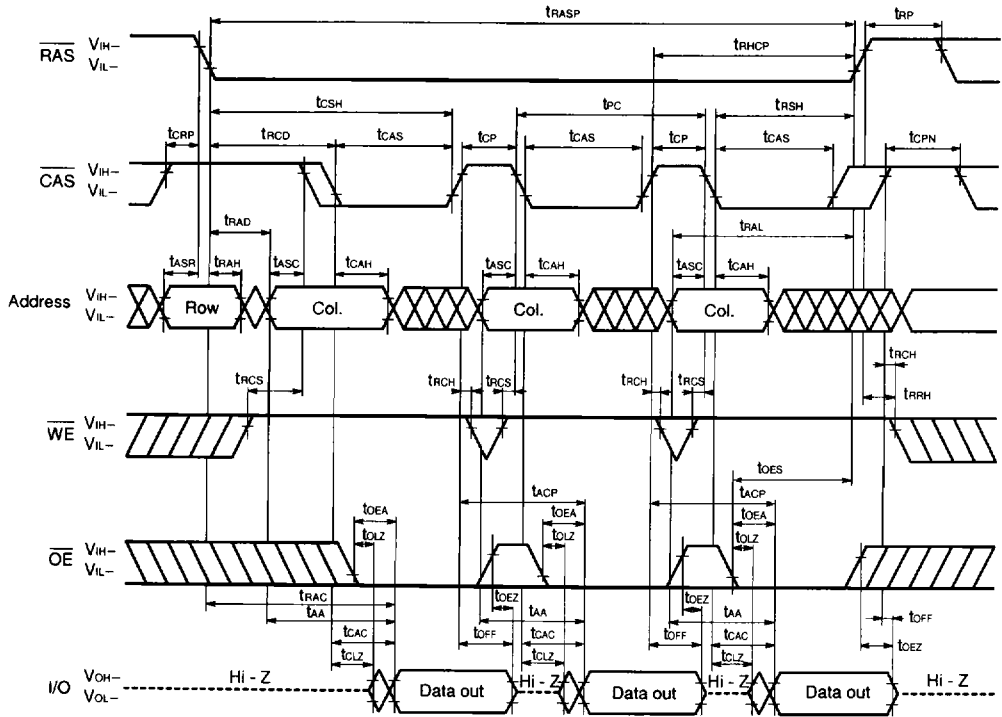


Read Modify Write Cycle



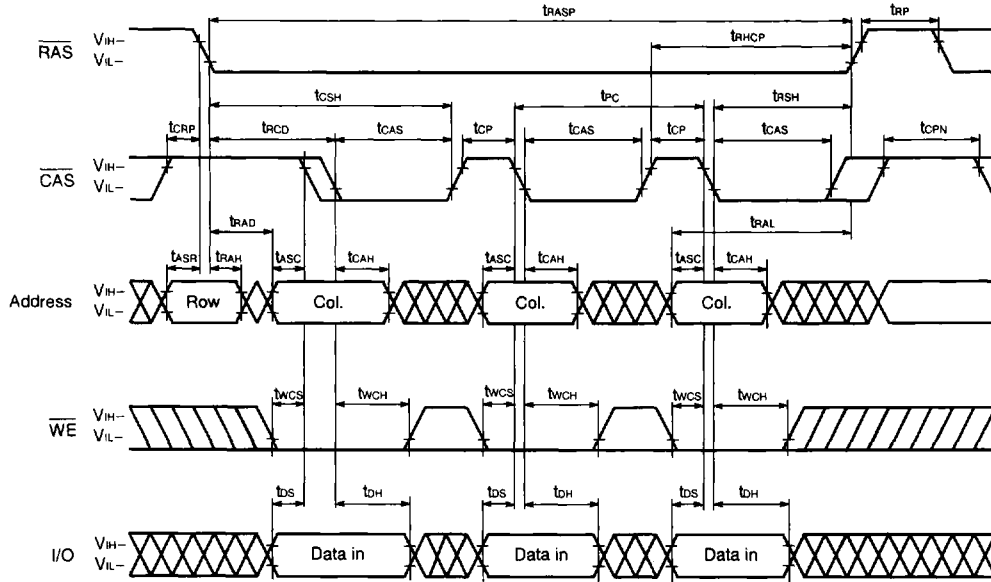


**Fast Page Mode Read Cycle**



**Remark** In the fast page mode, read, write and read modify write cycles are available for each of the consecutive CAS cycles within the same RAS cycle.

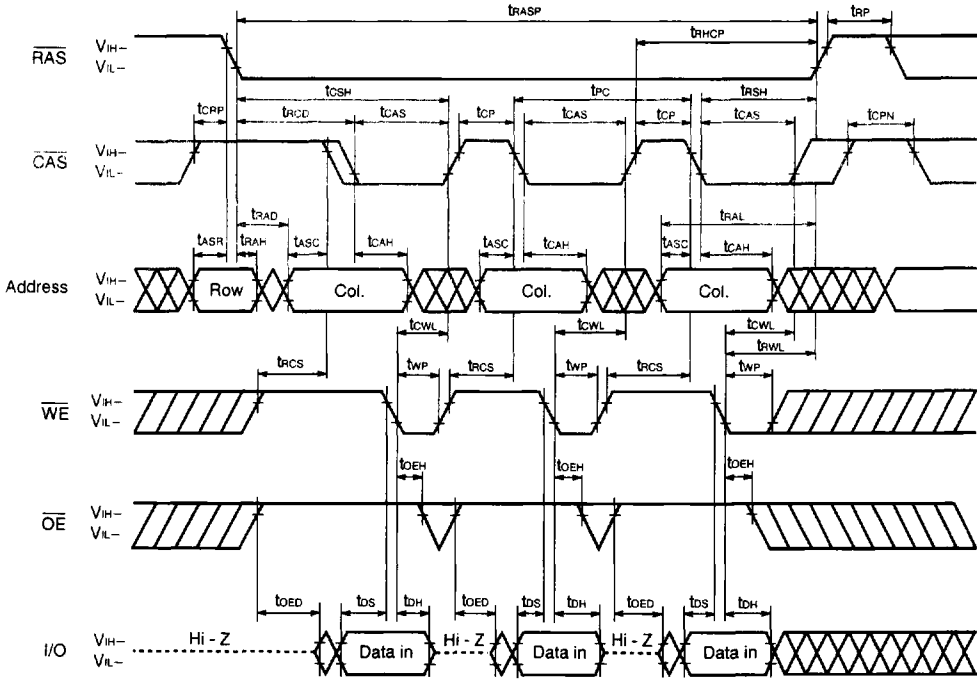
**Fast Page Mode Early Write Cycle**



**Remark**  $\overline{OE}$ : Don't care

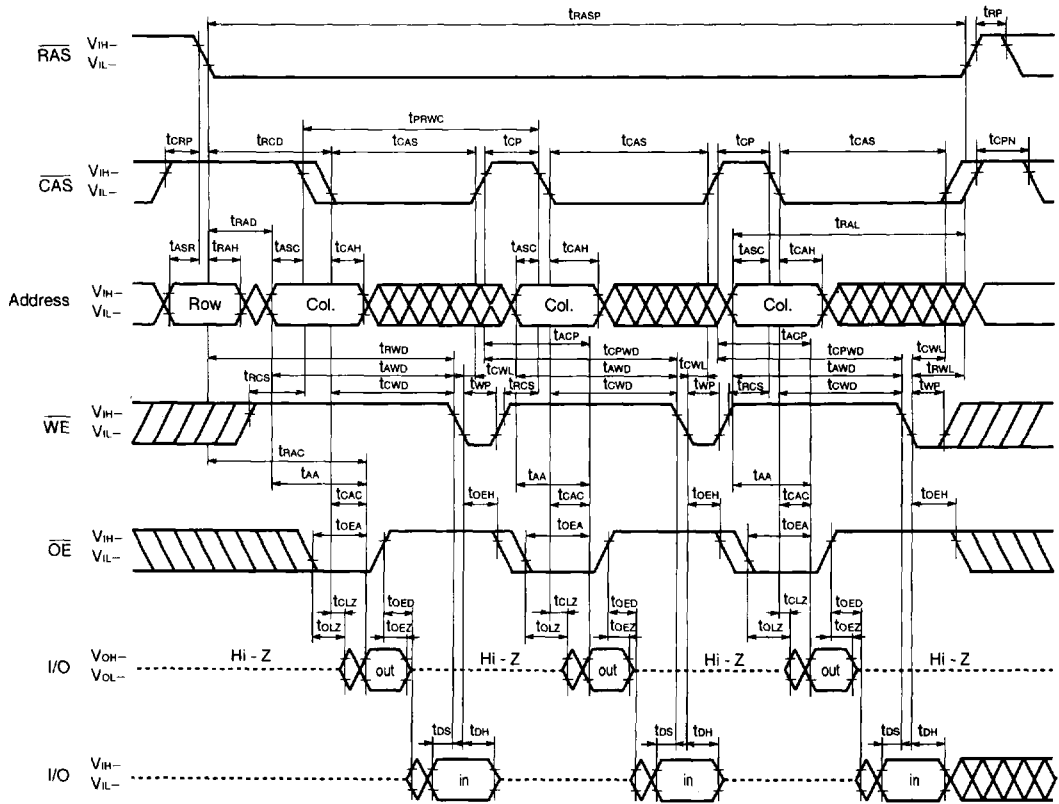
In the fast page mode, read, write and read modify write cycles are available for each of the consecutive  $\overline{CAS}$  cycles within the same RAS cycle.

**Fast Page Mode Late Write Cycle**



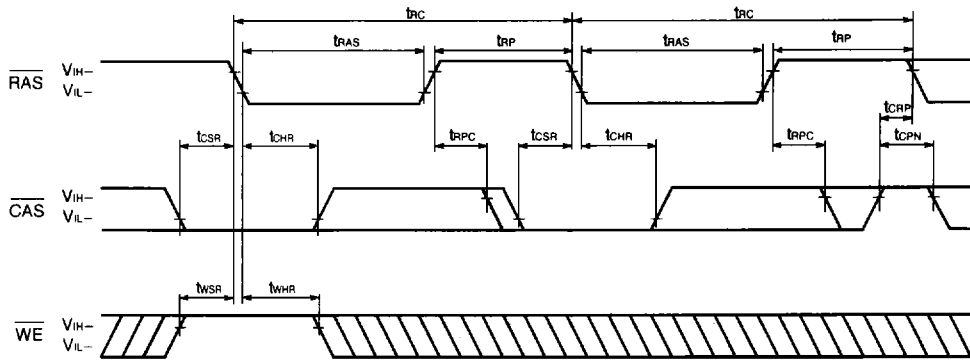
**Remark** In the fast page mode, read, write and read modify write cycles are available for each of the consecutive  $\overline{\text{CAS}}$  cycles within the same  $\overline{\text{RAS}}$  cycle.

Fast Page Mode Read Modify Write Cycle



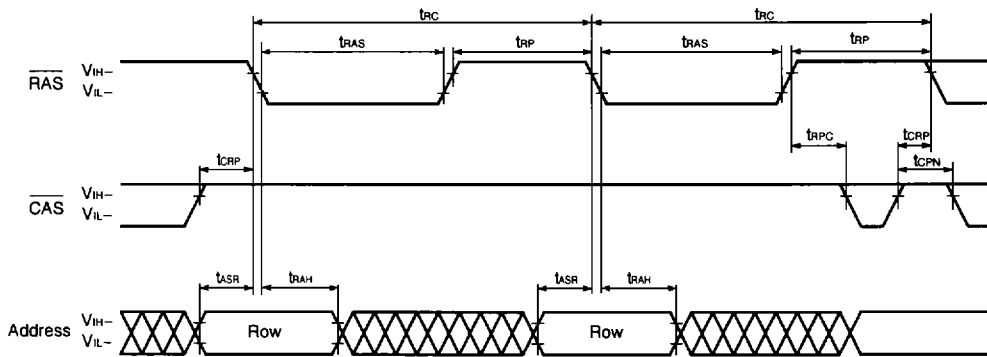
**Remark** In the fast page mode, read, write and read modify write cycles are available for each of the consecutive  $\overline{CAS}$  cycles within the same RAS cycle.

**CAS Before RAS Refresh Cycle**



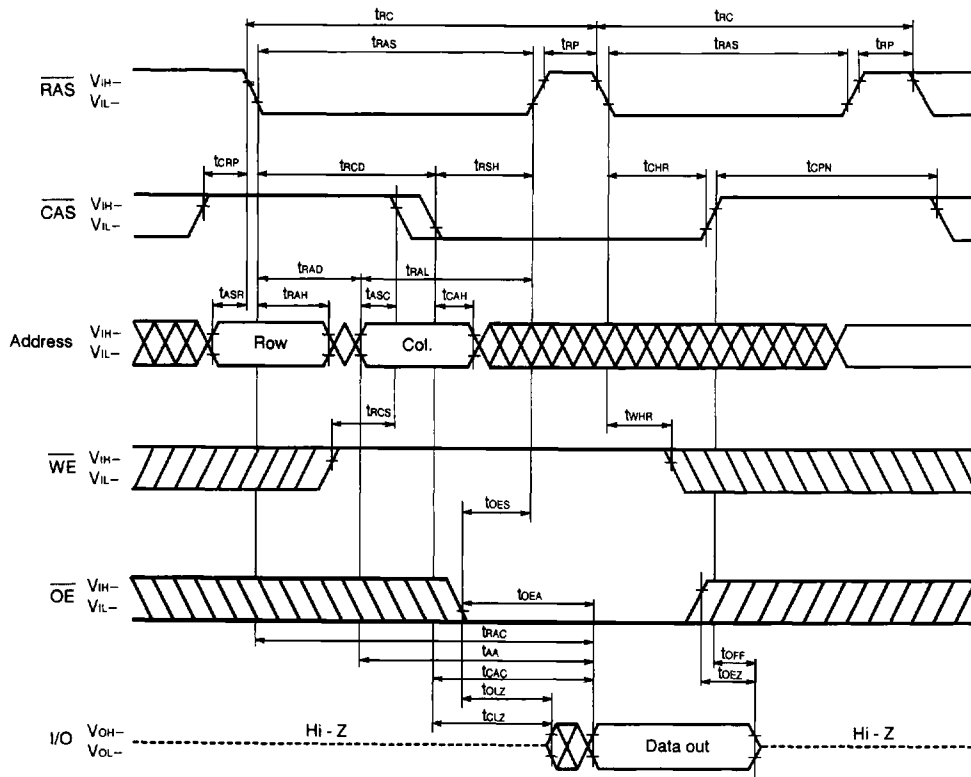
**Remark** Address,  $\overline{OE}$ : Don't care I/O: Hi-Z

**RAS Only Refresh Cycle**

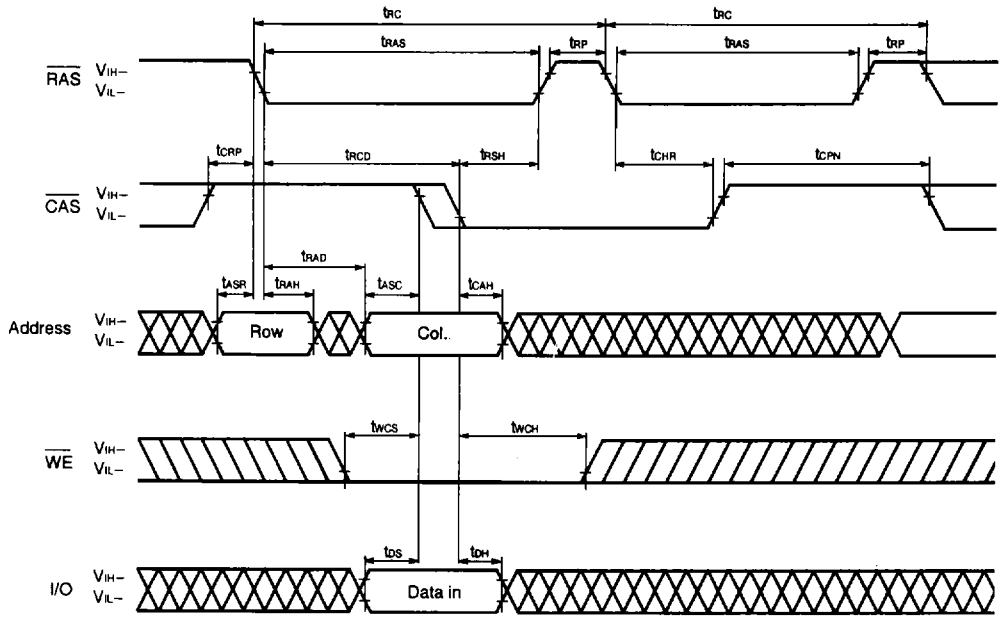


**Remark**  $\overline{WE}$ ,  $\overline{OE}$ : Don't care I/O: Hi-Z

Hidden Refresh Cycle (Read)

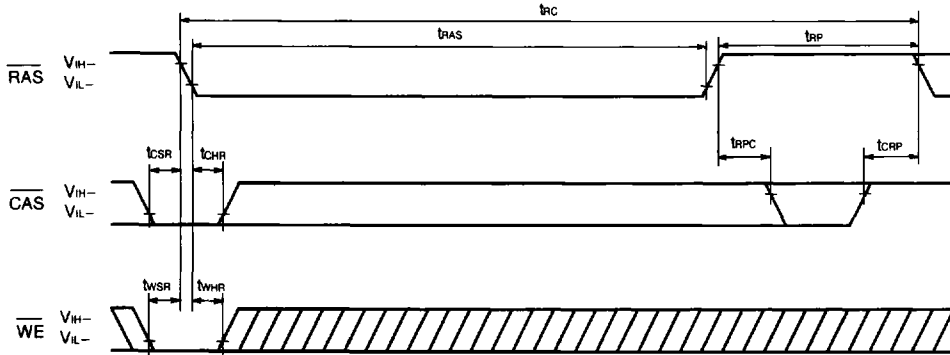


**Hidden Refresh Cycle (Write)**



**Remark**  $\overline{OE}$ : Don't care

**Test Mode Set Cycle ( $\overline{WE}$ ,  $\overline{CAS}$  Before  $\overline{RAS}$  Refresh Cycle)**



**Remark** Address,  $\overline{OE}$ : Don't care I/O: Hi - Z

**Test Mode**

By using the test mode, the test time can be reduced. The reason for this is that, the memory emulates the X 8-bit structure during test mode.

**(1) Setting the mode**

Executing the test mode cycle ( $\overline{WE}$ ,  $\overline{CAS}$  before  $\overline{RAS}$  refresh cycle) sets the test mode.

**(2) Write/read operation**

When either a "0" or a "1" is written to the input pin in test mode, this data is written to 8 bits of memory cell.

Next, when the data is read from the output pin at the same address, the cell can be checked.

Output="1": Normal write (all memory cells)

Output="0": Abnormal write

**(3) Refresh**

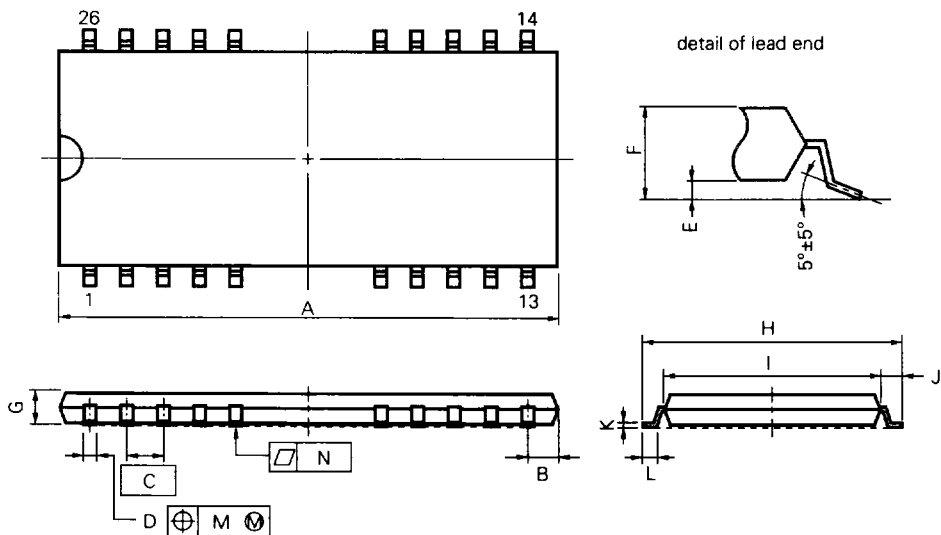
Refresh in the test mode must be performed with the  $\overline{RAS}$  /  $\overline{CAS}$  cycle or with the  $\overline{WE}$ ,  $\overline{CAS}$  before  $\overline{RAS}$  refresh cycle. The  $\overline{WE}$ ,  $\overline{CAS}$  before  $\overline{RAS}$  refresh cycle use the same counter as the  $\overline{CAS}$  before  $\overline{RAS}$  refresh's internal counter.

**(4) Mode Cancellation**

The test mode is cancelled by executing one cycle of  $\overline{RAS}$  only refresh cycle or  $\overline{CAS}$  before  $\overline{RAS}$  refresh cycle.



**Package Drawings**  
**26 PIN PLASTIC TSOP(III) (300 mil)**



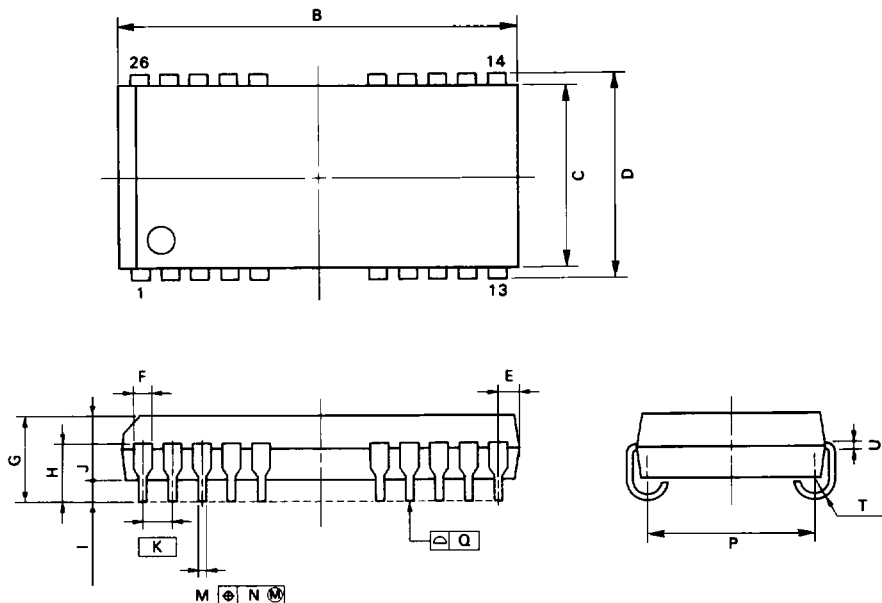
**NOTE**

Each lead centerline is located within 0.21 mm (0.009 inch) of its true position (T.P.) at maximum material condition.

S26GS-50-9JD-2

ITEM	MILLIMETERS	INCHES
A	17.54 MAX.	0.691 MAX.
B	1.18 MAX.	0.047 MAX.
C	1.27 (T.P.)	0.050 (T.P.)
D	0.40±0.10	0.016 <sup>+0.004</sup> <sub>-0.005</sub>
E	0.05±0.05	0.002±0.002
F	1.13 MAX.	0.045 MAX.
G	1.0	0.039
H	9.22±0.2	0.363±0.008
I	7.62±0.1	0.300±0.004
J	0.8±0.2	0.031 <sup>+0.009</sup> <sub>-0.008</sub>
K	0.125 <sup>+0.10</sup> <sub>-0.05</sub>	0.005 <sup>+0.004</sup> <sub>-0.002</sub>
L	0.5±0.1	0.020 <sup>+0.004</sup> <sub>-0.005</sub>
M	0.21	0.009
N	0.10	0.004

26PIN PLASTIC SOJ (300 mil)



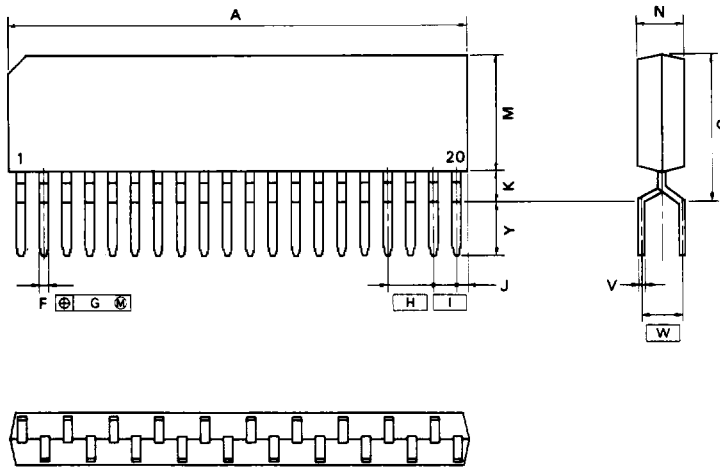
P26LA-50A-1

**NOTE**

Each lead centerline is located within 0.12 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
B	17.4 <sup>+0.2</sup> <sub>-0.35</sub>	0.685 <sup>+0.008</sup> <sub>-0.013</sub>
C	7.57	0.298
D	8.47 <sup>+0.2</sup>	0.333 <sup>+0.008</sup> <sub>-0.008</sub>
E	1.08 <sup>+0.15</sup>	0.043 <sup>+0.006</sup> <sub>-0.007</sub>
F	0.6	0.024
G	3.5 <sup>+0.2</sup>	0.138 <sup>+0.008</sup>
H	2.4 <sup>+0.2</sup>	0.094 <sup>+0.008</sup> <sub>-0.008</sub>
I	0.8 MIN.	0.031 MIN.
J	2.6	0.102
K	1.27(T.P.)	0.050(T.P.)
M	0.40 <sup>+0.10</sup>	0.016 <sup>+0.004</sup> <sub>-0.006</sub>
N	0.12	0.005
P	6.73 <sup>+0.20</sup>	0.265 <sup>+0.008</sup>
Q	0.15	0.006
T	R 0.85	R 0.033
U	0.20 <sup>+0.10</sup> <sub>-0.08</sub>	0.008 <sup>+0.004</sup> <sub>-0.002</sub>

20PIN PLASTIC ZIP (400 mil)



**NOTE**

Each lead centerline is located within 0.25 mm (0.010 inch) of its true position (T.P.) at maximum material condition.

P20V-254-400A-1

ITEM	MILLIMETERS	INCHES
A	26.67 MAX.	1.050 MAX.
F	0.5 <sup>±0.1</sup>	0.020 <sup>-0.008</sup>
G	φ0.25	φ0.010
H	2.54	0.100
I	1.27	0.050
J	1.27 MAX.	0.050 MAX.
K	1.0 MIN.	0.039 MIN.
M	8.9 MAX.	0.350 MAX.
N	2.8 <sup>±0.2</sup>	0.110 <sup>-0.008</sup>
Q	10.16 MAX.	0.400 MAX.
V	0.25 <sup>-0.02</sup>	0.010 <sup>-0.003</sup>
W	2.54	0.100
Y	3.3 <sup>±0.6</sup>	0.130 <sup>±0.02</sup>

**Recommended Soldering Conditions**

The following conditions (see tables below and next page) must be met for soldering conditions of the μPD424400.

For more details, refer to our document "SEMICONDUCTOR DEVICE MOUNTING TECHNOLOGY MANUAL" (IEI-1207).

Please consult with our sales offices in case other soldering process is used, or in case the soldering is done under different conditions.

**Types of Surface Mount Device**

μPD424400GS : 26-pin plastic TSOP(II) (300 mil)

Soldering process	Soldering conditions	Symbol
Infrared ray reflow	Peak temperature of package surface : 235 °C or below, Reflow time : 30 seconds or below (210 °C or higher), Number of reflow processes: MAX. 2 Exposure limit <sup>Note</sup> : 7 days (10 hours pre-baking is required at 125 °C afterwards)  <b>[Remark]</b> (1) Please start the second reflow process after the temperature, raised by the first reflow process, returns to normal. (2) Please avoid removing the residual flux with water after the first reflow process .	IR35-107-2
VPS	Peak temperature of package : 215 °C or below, Reflow time : 40 seconds or below (200 °C or higher), Number of reflow processes: MAX. 2 Exposure limit <sup>Note</sup> : 7 days (10 hours pre-baking is required at 125 °C afterwards)  <b>[Remark]</b> (1) Please start the second reflow process after the temperature, raised by the first reflow process, returns to normal. (2) Please avoid removing the residual flux with water after the first reflow process .	VP15-107-2
Partial heating method	Terminal temperature: 300 °C or below, Time : 3 seconds or below (Per one side of the device).	_____

**Note** Exposure limit before soldering after dry-pack package is opened.

Storage conditions: 25 °C and relative humidity at 65 % or less.

**Caution** Do not apply more than one soldering method at any one time, except for "Partial heating method".

μPD424400LA : 26-pin plastic SOJ (300 mil)

Soldering process	Soldering conditions	Symbol
Infrared ray reflow	Peak temperature of package surface : 235 °C or below, Reflow time: 30 seconds or below (210 °C or higher), Number of reflow processes: MAX. 2 Exposure limit <sup>Note</sup> : 7 days (20 hours pre-baking is required at 125 °C afterwards)  <b>[Remark]</b> (1) Please start the second reflow process after the temperature, raised by the first reflow process, returns to normal. (2) Please avoid removing the residual flux with water after the first reflow process.	IR35-207-2
VPS	Peak temperature of package : 215 °C or below, Reflow time : 40 seconds or below (200 °C or higher), Number of reflow processes: MAX. 2 Exposure limit <sup>Note</sup> : 7 days (20 hours pre-baking is required at 125 °C afterwards)  <b>[Remark]</b> (1) Please start the second reflow process after the temperature, raised by the first reflow process, returns to normal. (2) Please avoid removing the residual flux with water after the first reflow process.	VP15-207-2
Partial heating method	Terminal temperature: 300 °C or below, Time : 3 seconds or below (Per one side of the device).	_____

**Note** Exposure limit before soldering after dry-pack package is opened.  
 Storage conditions: 25 °C and relative humidity at 65 % or less.

**Caution** Do not apply more than one soldering method at any one time, except for "Partial heating method".

**Type of Through Hole Mount Device**

μPD424400V : 26-pin plastic ZIP (400 mil)

Soldering process	Soldering conditions
Wave soldering	Solder temperature : 260 °C or below, Flow time : 10 seconds or below
Partial heating method	Terminal temperature : 260 °C below, Time : 10 seconds or below

**Caution** Do not jet molten solder on the surface of package.